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# Automation in urban public transportation

February 2016

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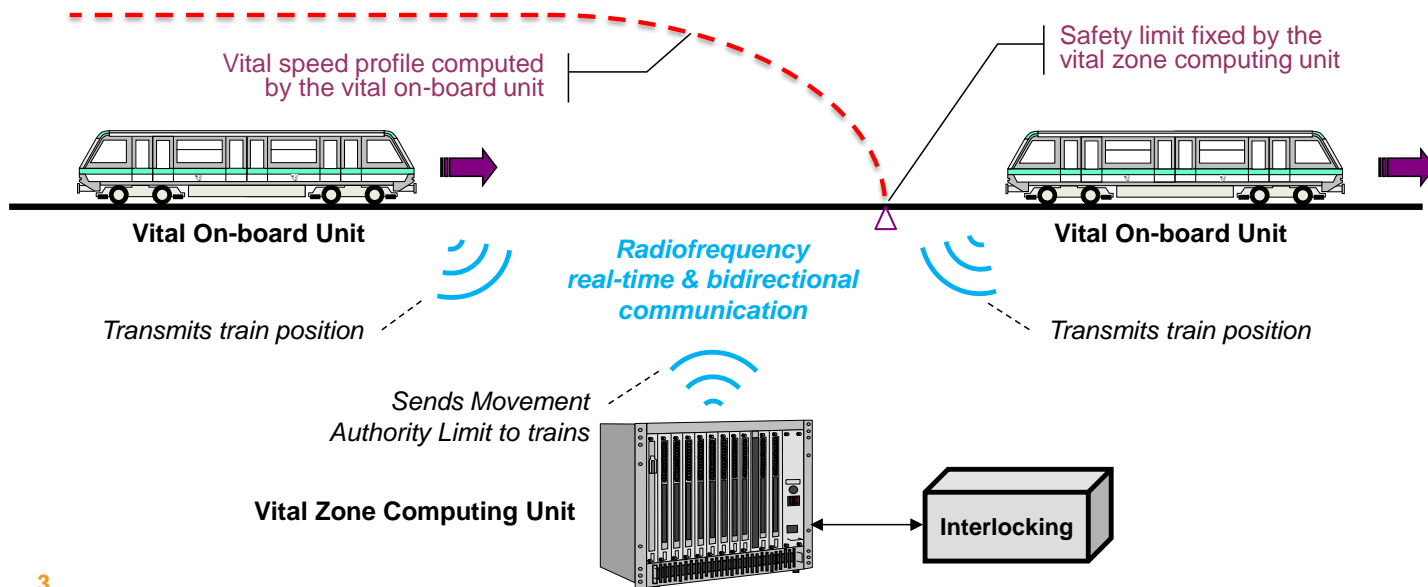


# WHAT IS CBTC ?

# Communication Based Train Control Systems

## The new market standard for signaling systems

- ▶ Most often using radio frequencies for train to track communication



3



# AUTOMATION RATP's ACHIEVEMENTS

# Levels of automation

## FOUR LEVELS OF AUTOMATION



### CONTROLLED MANUAL DRIVING

The driver manages all aspects of driving the train manually.

GOA1



### SEMI-AUTOMATED CONTROL WITH DRIVER

The train is operated using automated controls. The driver is in charge of opening and closing doors, authorises the start-up of the train, monitors the tracks and handles unexpected situations.

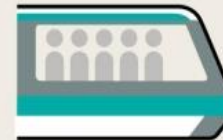
GOA2



### AUTOMATED DRIVING WITH ON-BOARD STAFF

A person (not a driver) is on board to open and close doors and handle incidents.

GOA3



### FULLY AUTOMATED DRIVING

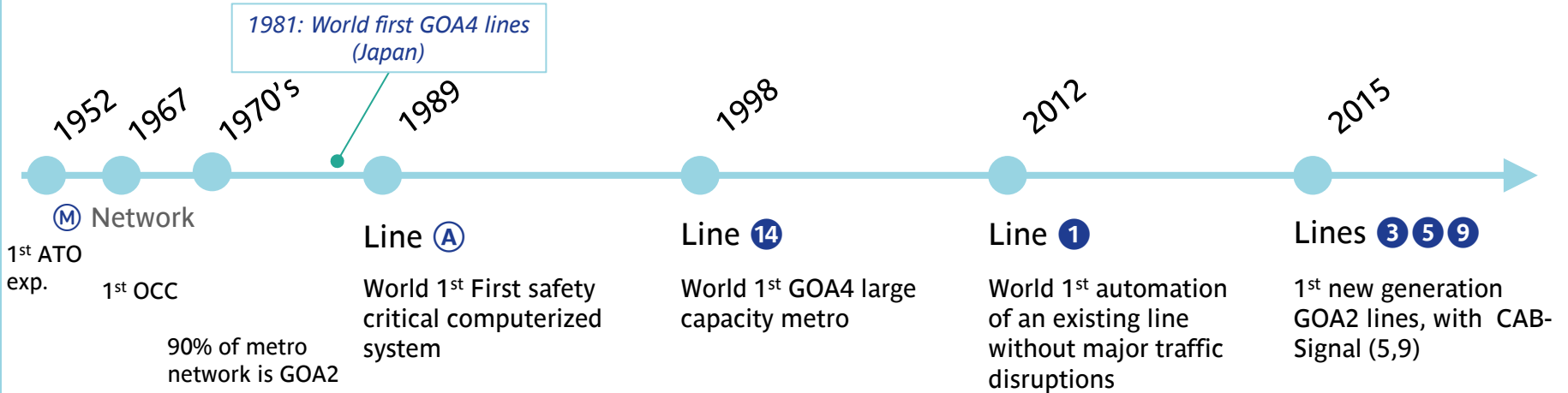
No staff aboard. The control system manages all operations, supervised remotely by a control centre.

GOA4

## 2 | ACHIEVEMENTS

# RATP's first times

Automated metro is the result of a long story of innovation that began in the 50's.





# Line 14 1998

The first fully-automated large capacity metro



## 2 | ACHIEVEMENTS

# Line 14 construction

In 1987, RATP proposes a solution to relieve traffic on the RER A. Construction starts in 1992, first tests of the automated system begin in 1995 and the line opens in 1998.

### SYSTEM VISION

#### A whole system to re-think :

- organization (maintenance and operation),
- Passenger service (stations, staff presence),
- And technical systems with new safety challenges

## Large capacity auto. metro

Line 14 automated system prefigures modern CBTC (*Communication Based Train Control*)

### TECHNICAL CHALLENGES

- Infrastructure designed for performance : Distance between stations, tracks (straight profile, chain profile )
- Safety criteria allocated on every system component
- Board/tracks data transmission via Magnetic Loops (ATP/ATO : Automatic train protection and automatic train operation)
- **Capitalizing on SACEM achievements** : encoded processor, industrialization of B method
- Innovations : Video surveillance by radio

**Innovation lies above all in the operational management model.**



# Line 1 2012

World first  
automation of an  
existing line  
without major  
traffic disruptions

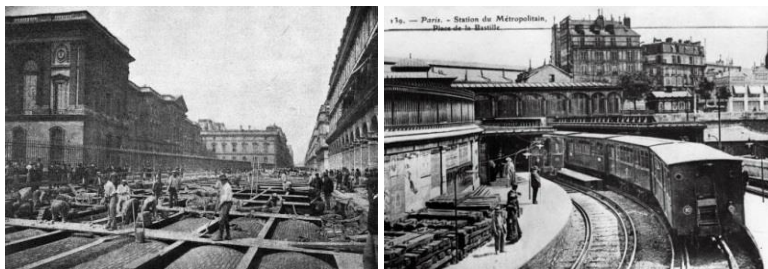
## 2 | ACHIEVEMENTS

# Line 1 automation

Built in 1900, Line 1 is the oldest, fastest and most crowded line of the Paris metro network. It is heavily loaded during rush hours and also off-peak hours, weekends & holiday periods. In 2003, RATP launches an automation feasibility study.

## Double challenge

Automation of a 100-year old line without major traffic disruption



## A 100-YEAR OLD LINE

Old infrastructures and specific configuration, implying

- Renewal of all the signalling equipment
- Infrastructure adaptation (Energy, tracks, platforms)
- Curved stations management

## NO TRAFFIC INTERRUPTION

Automatizing a line without traffic disruption implies strong **operational constraints** :

- Work shifts of 3 hours per night
- Maintenance works “as usual”
- Mixed mode operation (trains with and without drivers)



# Lines 3, 5, 9 2015

GOA2 new  
generation

# New generation GOA2

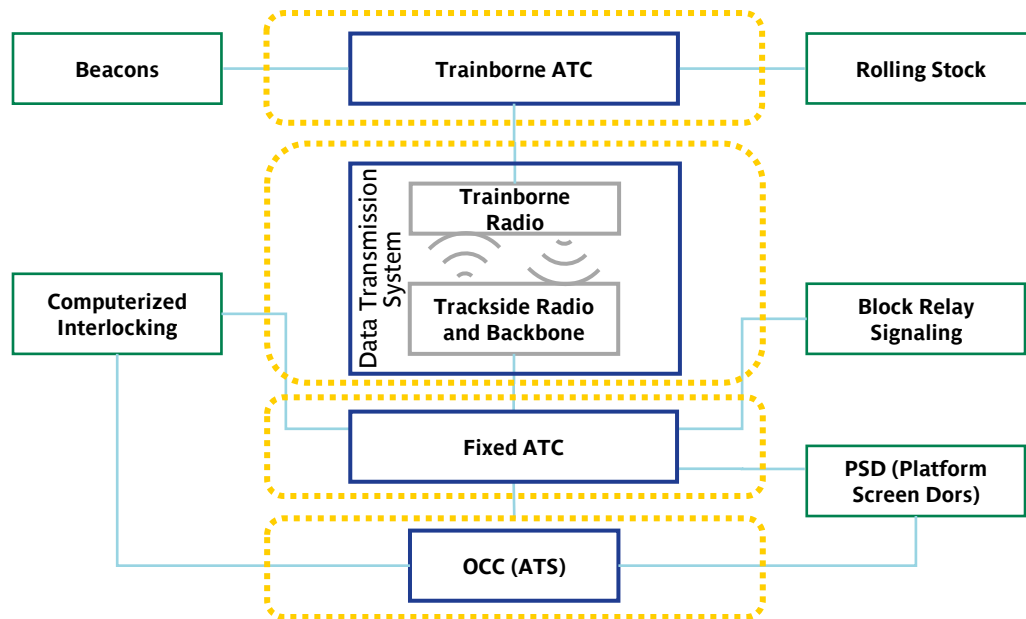
OCTYS principles....

## MAIN FEATURES

- transmission via free propagation radio @ 5.9 GHz
- System architecture compatible with international standards (IEC62-290 & Modurban)
- Software safety demonstration by
  - B Method or
  - **Formal proof**– innovation

## INTERCHANGEABILITY

4 Separate contract shares for GOA2 CBTC





# ADVANTAGES OF THE AUTOMATED METRO

## 4 kinds of improvement

Automated system has many benefits.



Better Safety  
(GoA2, GoA3, GoA4)



Better socio-economic  
performance (GoA4)



Better functional  
performance  
(GoA2, GOA3, GoA4)



Better environmental  
performance

## Better safety

0 accidents

No accident on automated line in Paris.

WARNING : The maintaining of drivers' competences, which are needed during rare automated system breakdowns, is a major challenge.

Losing the barriers between the responsibility of the automatic pilot and the driver can prove to be disastrous.

### HUMAN FACTOR

Compared error rates

- Human operator: 10-3/h (10-4/h if well trained)
- Automated system : <10-9/h

### CONTINUOUS CONTROL

Signal passed at danger or overspeed are

- anticipated
- controlled
- And leads to emergency stopping of the train

### TRACK/PLATFORM INTERFACE



Platform screen doors prevent technical incidents and accidents



### 3 ADVANTAGES of Automated metro

## Better OPEX



### ADDITIONAL COSTS

- Maintenance of new functions and equipment

### DIRECT SAVINGS

- Less staff to operate
- Less maintenance on trains (less traction / braking commutations for instance)
- Energy savings

### OTHER SAVINGS

- Increased ridership
- Better service : less delay-related economic losses
- No more passenger accidents

**Return on investment  
within 15 years (line 1)**

### 3 ADVANTAGES of Automated metro

## Functional performance

#### CAPACITY

- Reduces headway  
*Line 1 and 14 can reach a headway of 85 seconds*
- No more driver cabin (GoA4) : better train capacity

#### ADAPTABILITY

- Possibility to add more trains instantaneously  
*Example : end of a music show*
- Reduced marginal cost of operation (enables to increase the service off peak for instance)

**+ 30%**  
**capacity**

For Paris line 1 when converted to GoA4.

Headway of 100s all day long on line 1 during heavy maintenance work on line A during summer

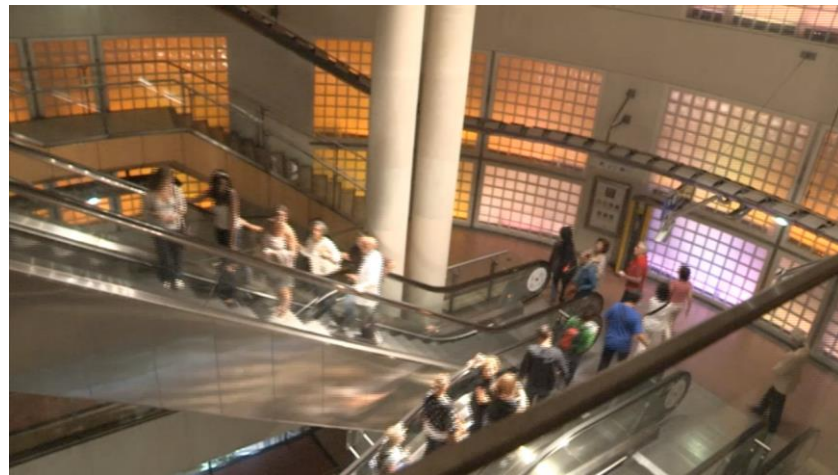
#### RELIABILITY

- Coasting and dwelling times are precisely controlled

#### RESILIENCE

- After an incident, back to normal within minutes

**98%**  
**satisfied**  
**passengers**



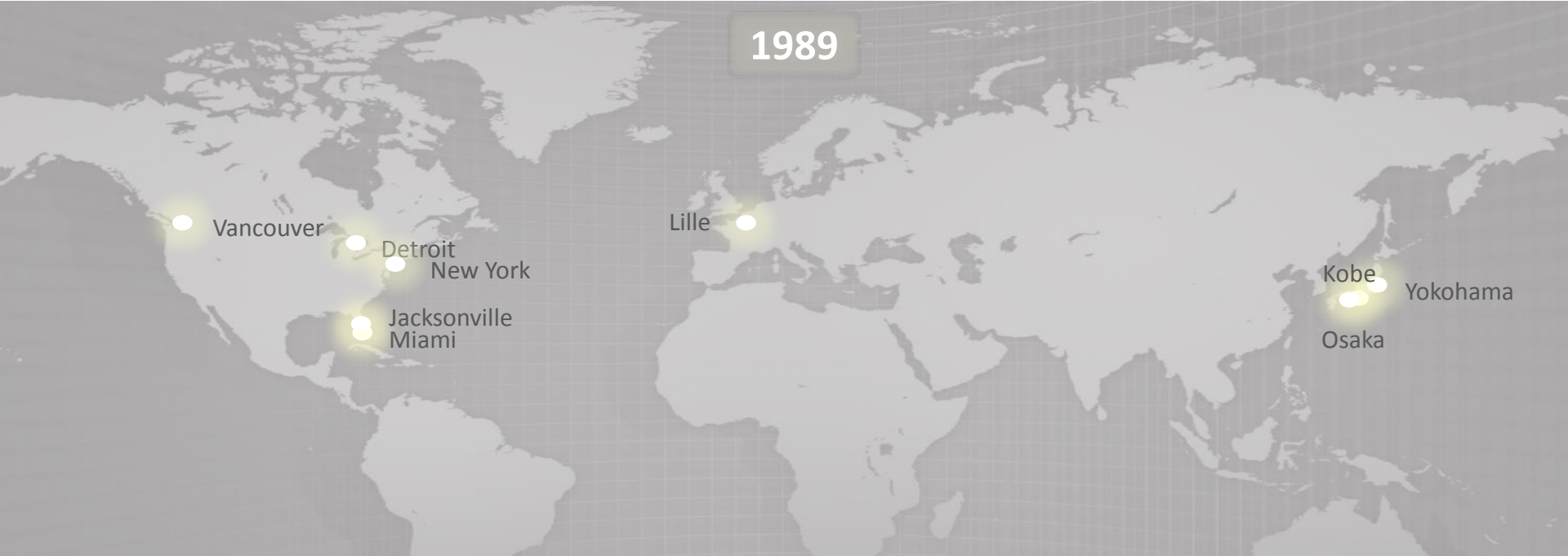


# TRENDS AND EVOLUTION OF AUTOMATIION IN THE WORLD

*UITP data from Observatory of automated metro*

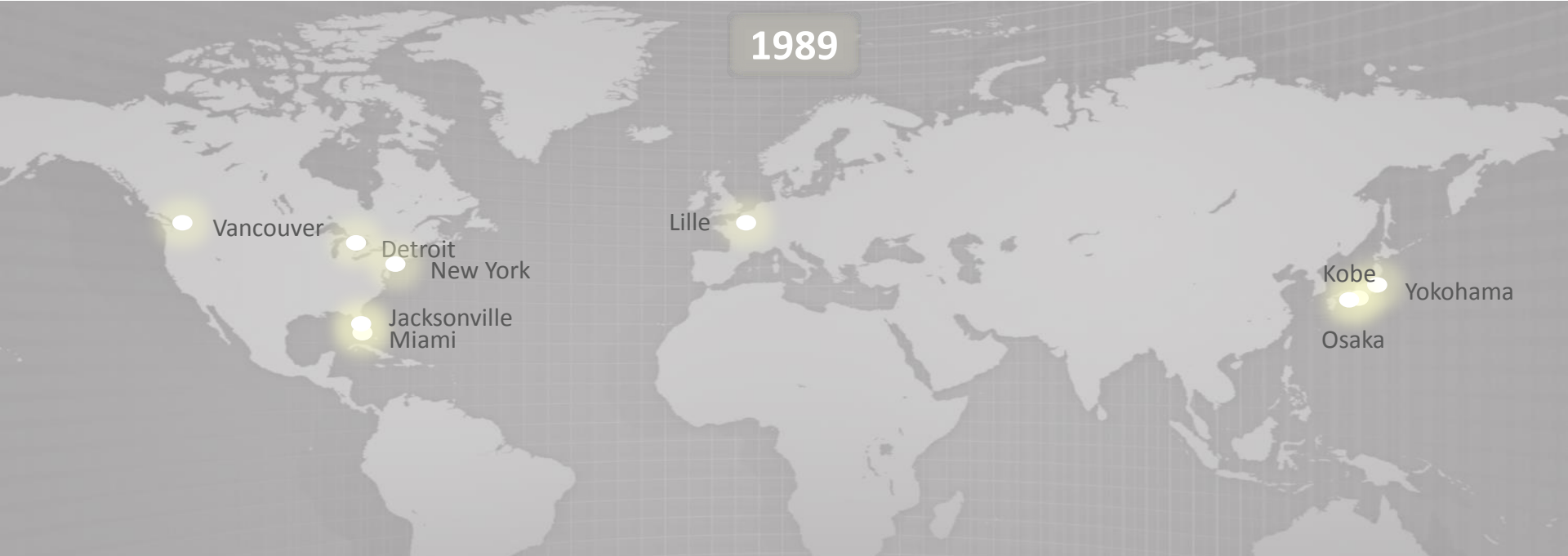
# PIONEERS ERA: 1980-90

99 km



# PIONEERS ERA: 1980-90

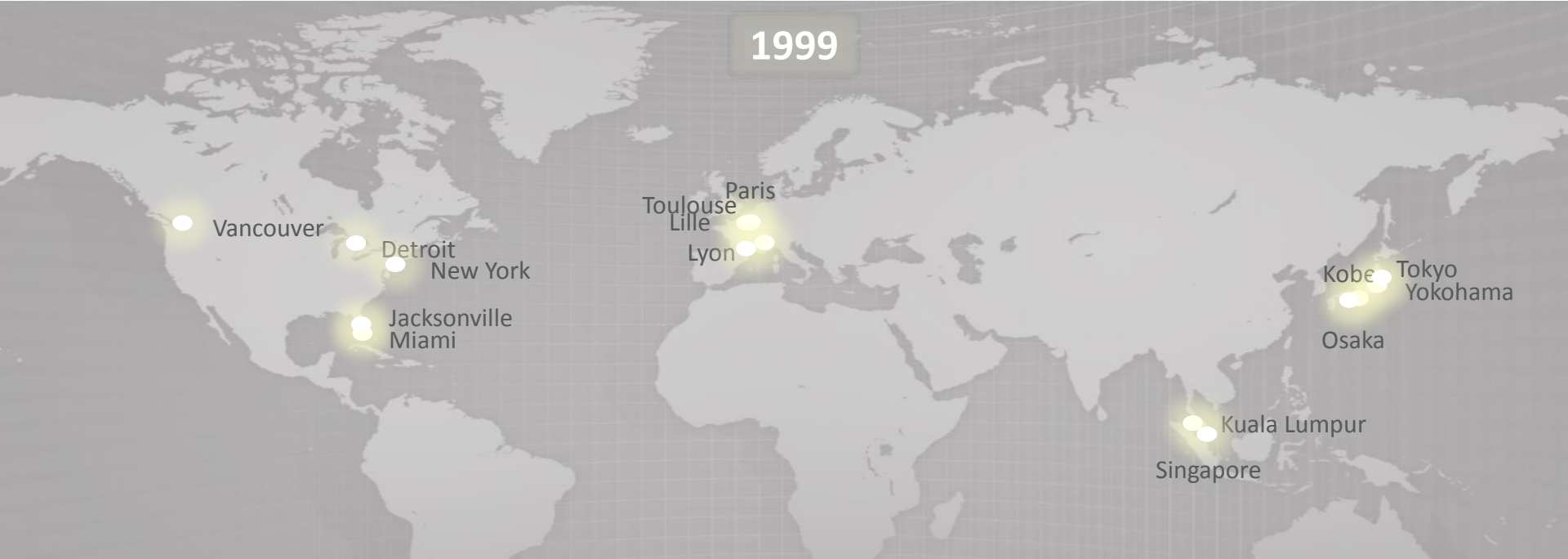
99 km



# EARLY ADOPTERS: 1990-2000

213 km

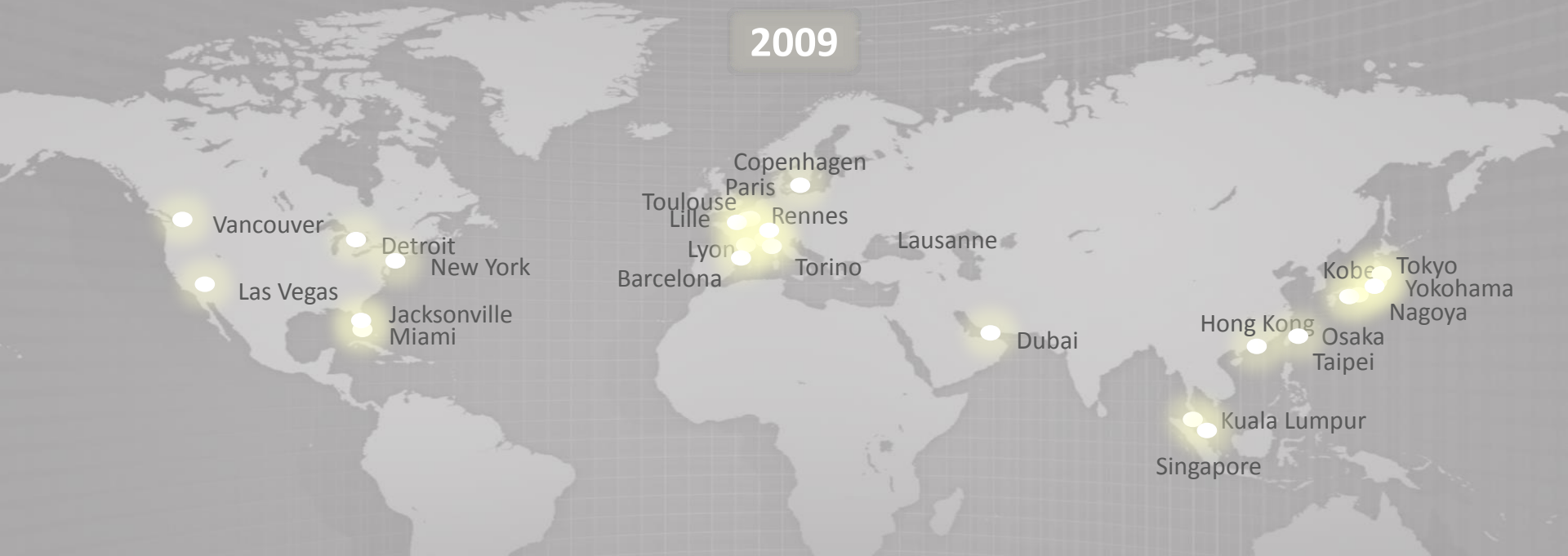
1999



# A PROVEN REALITY: 2000-2010

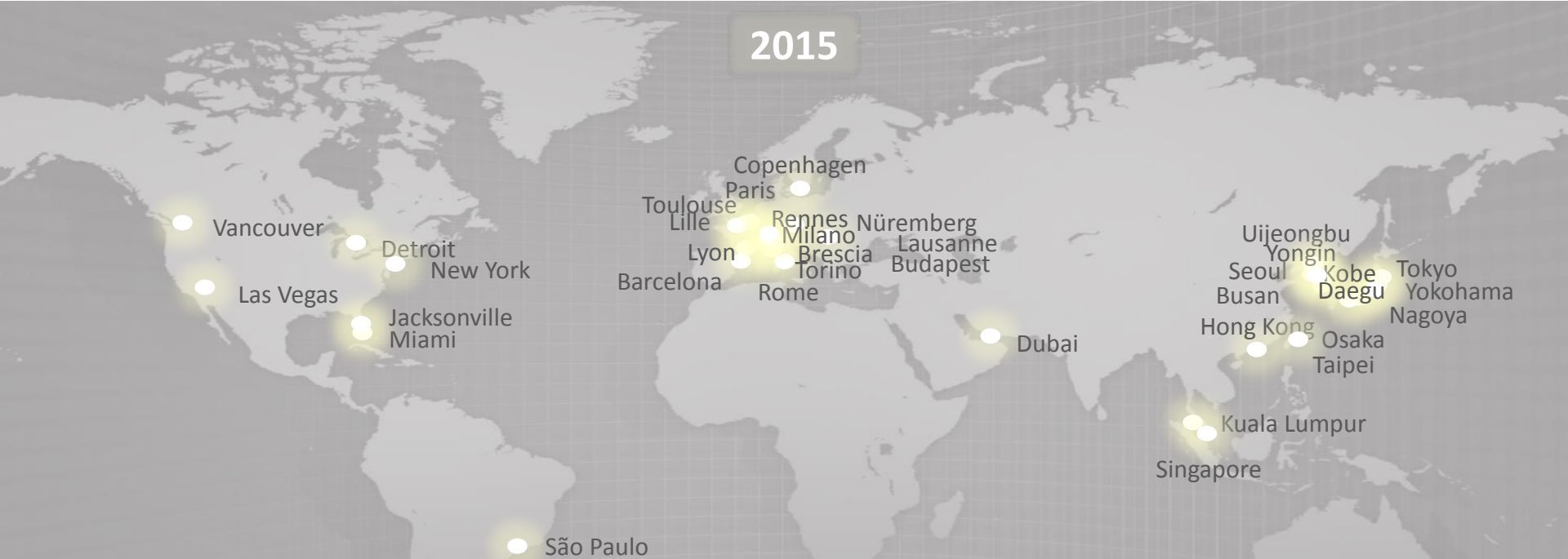
450 km

2009



# A PROVEN REALITY: 2010-TODAY

737 km





# EXPONENTIAL GROWTH! 2014-2025



future 2328 km

# AUTOMATION TODAY

737

km

UTO

54

lines

today

785

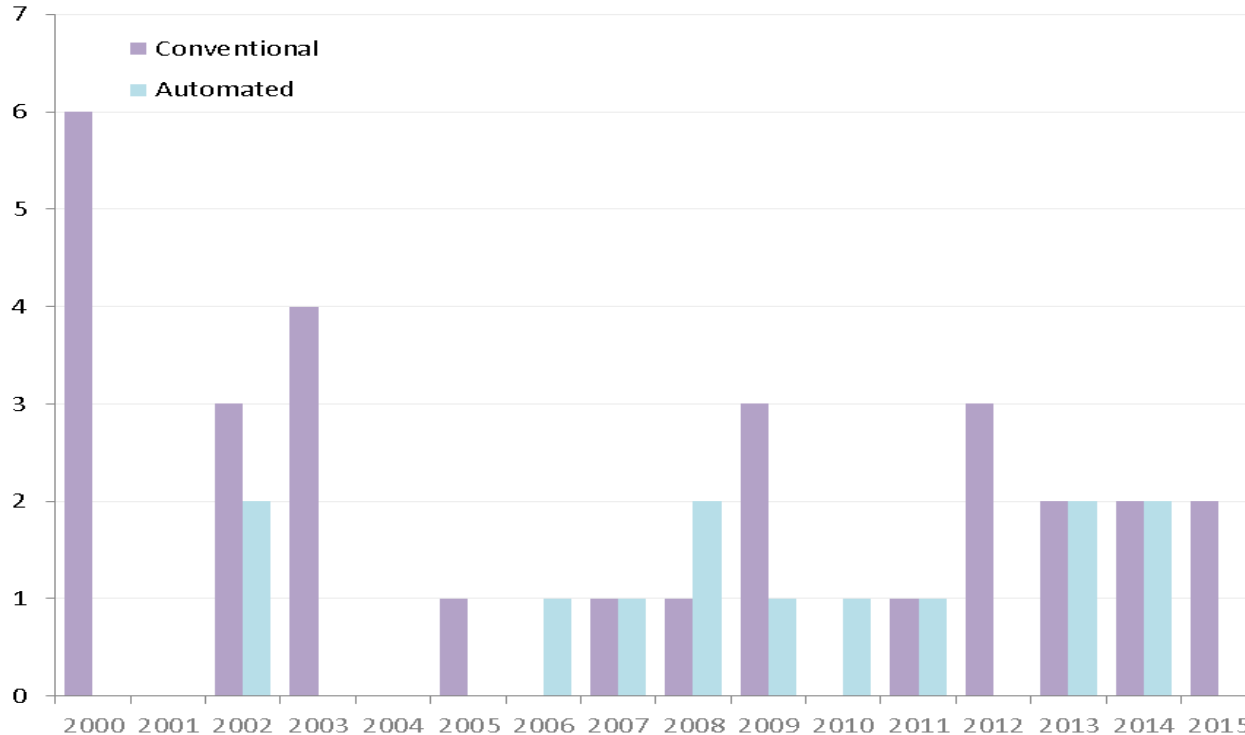
st.

36

cities

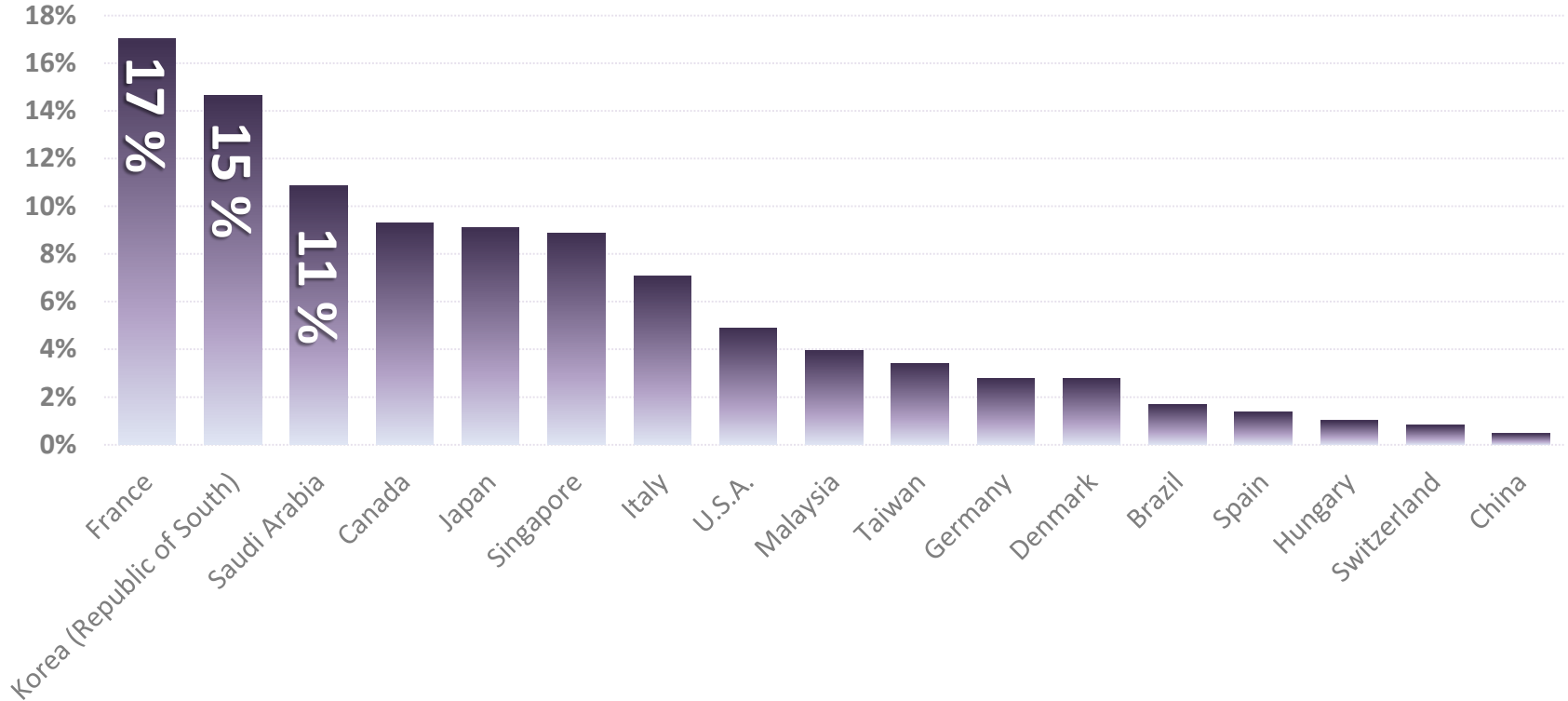
# AUTOMATION TODAY

## Europa New Conventional Lines vs UTO Lines



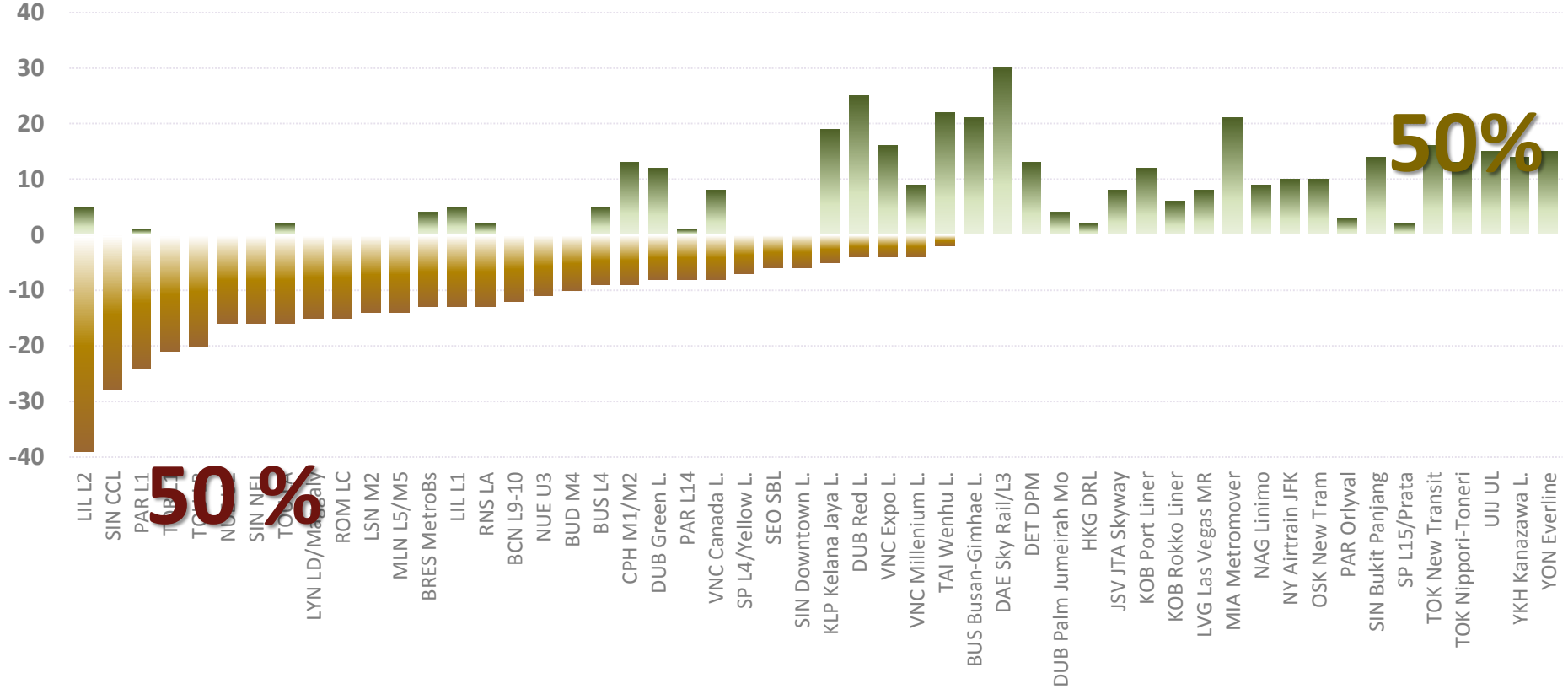
# AUTOMATION TODAY

## UTO % of km per Country



# AUTOMATION TODAY

Constructive models: underground vs elevated (# stations)



# TRENDS & EVOLUTION

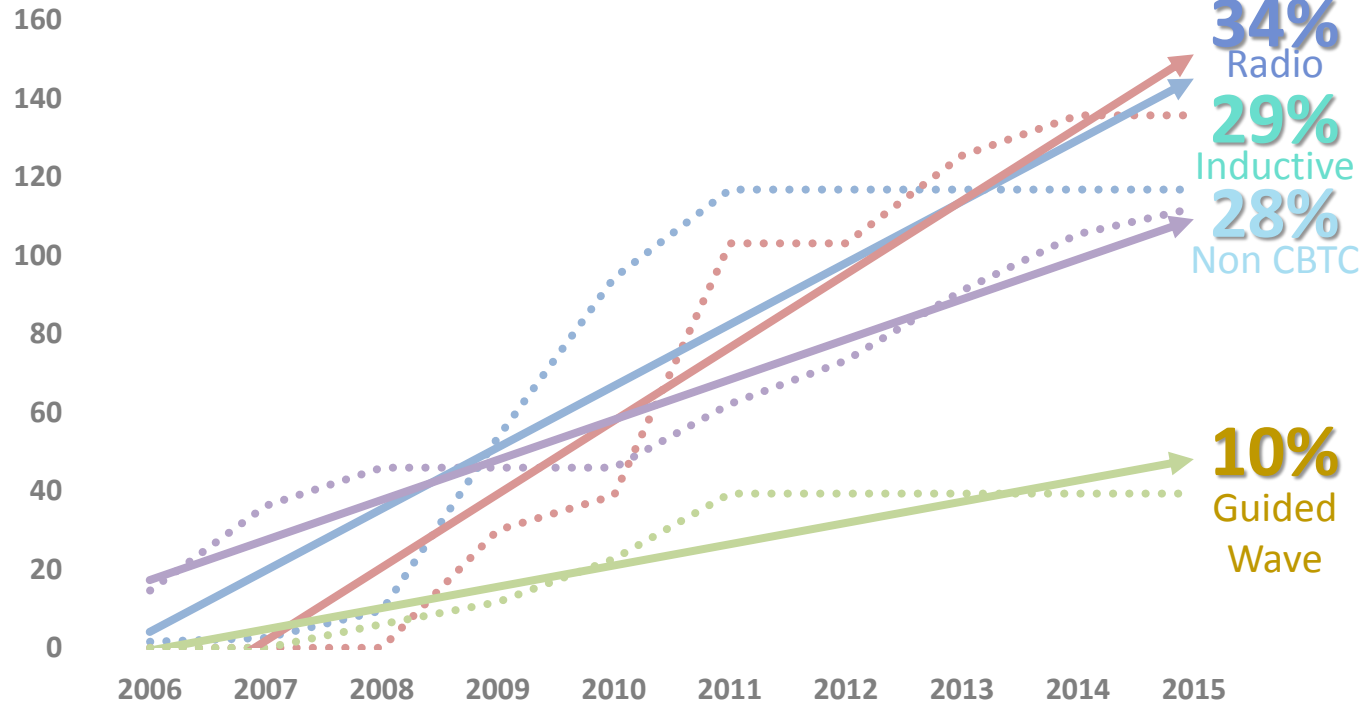
© Signaling Solutions: Share of Inductive loops – Radio -  $\mu$ Wave



Inductive Loop

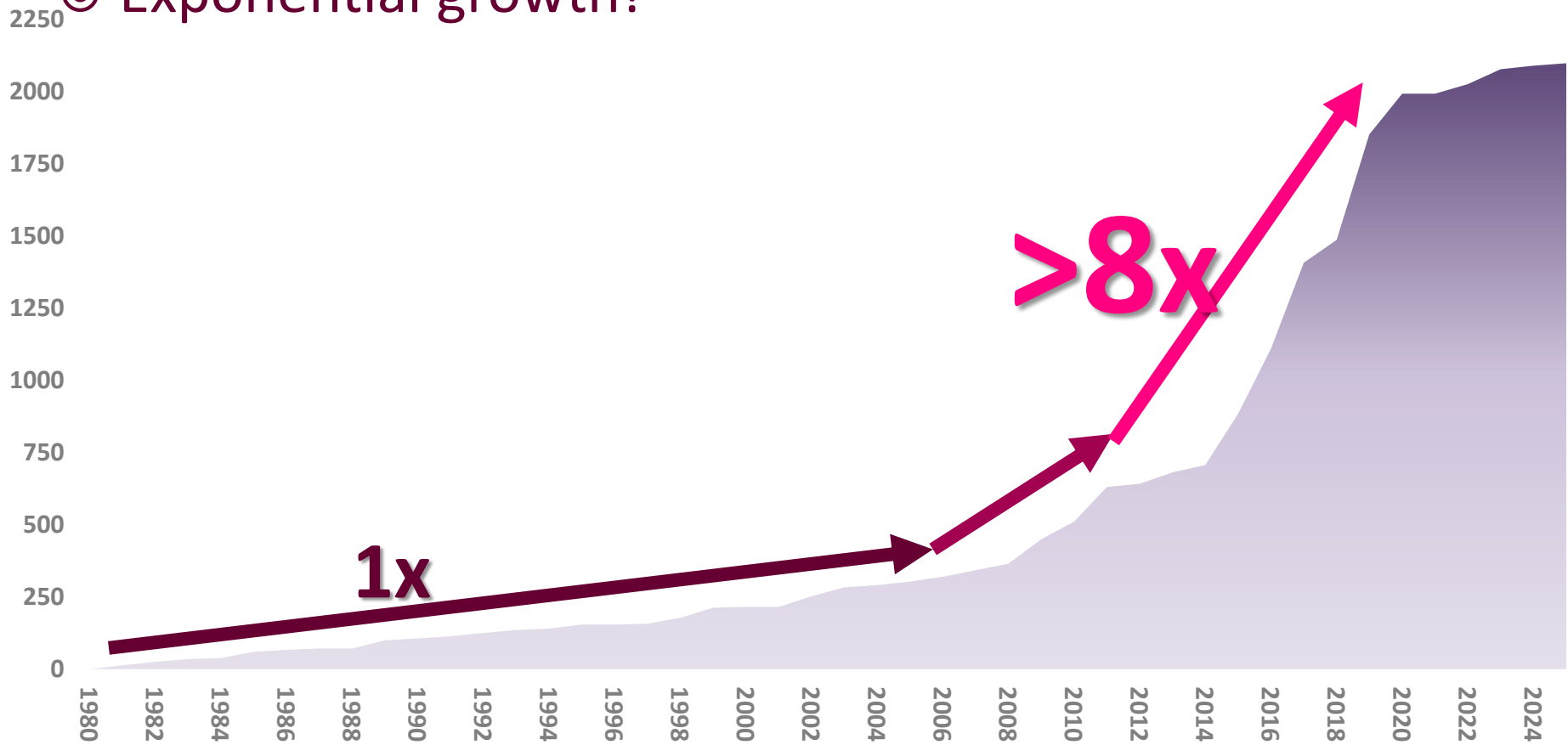


RF free propagation



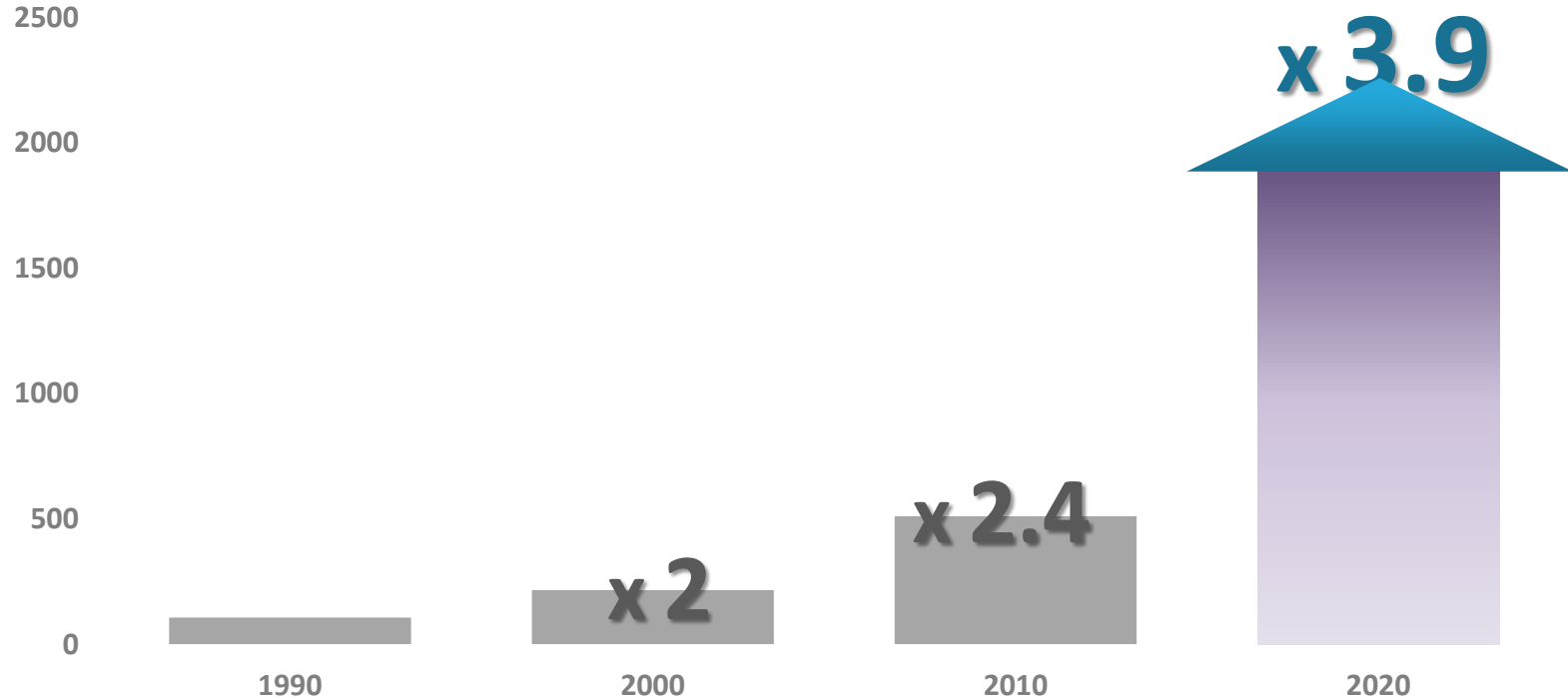
# FUTURE: GROWTH

⦿ Exponential growth!



# FUTURE: GROWTH

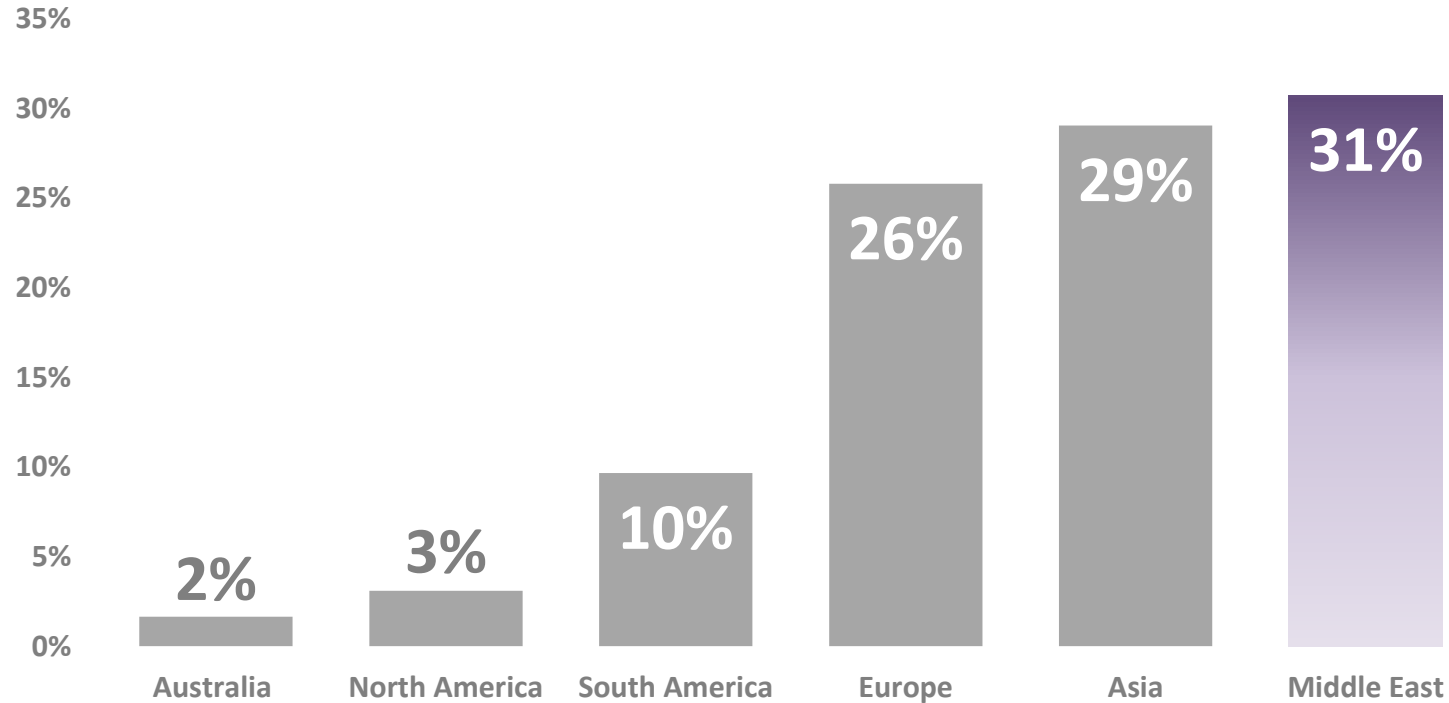
© Exponential growth! relative to previous decade





# FUTURE: GROWTH

© Worldwide growth distribution (*% of new km's 2015-25*)





# THE USE OF RADIO FREQUENCIES FOR SIGNALLING SYSTEMS

# CBTC

## Main criteria for radio frequency selection:

- Propagation (either in tunnels and in open air)
- Resilience (robustness to perturbations)
- Bandwidth (hundreds of kb/s required for CBTC)

## Common applications:

- Wifi based 2.4 GHz (or 5.1-5.8 GHz)
  - Open band (ISM) but more and more saturated with commercial Wifi, Bluetooth and Zigbee applications
- Wifi based 5.9 GHz
  - Not (yet) saturated band but subject to local licensing
- LTE based frequencies (4G/5G)
  - Dependency to radio-communication operators

## CBTC

**Several EU countries already use radio communication systems in the 5,9GHz range :**

- ▶ SNCF for freight trains : 5,915 GHz to 5,935 GHz
- ▶ RATP for Paris subway : 5,915 GHz to 5,935 GHz
- ▶ SYTRAL for Lyon subway : 5,915 GHz to 5,935 GHz
- ▶ Copenhagen : 5,925 GHz to 5,975 GHz
- ▶ Helsinki : 5,925 GHz to 5,960 GHz
- ▶ Malaga : 5,915 GHz to 5,935 GHz
- ▶ Lille : 5,915 GHz to 5,935 GHz

**All on a limited duration licensing scheme**

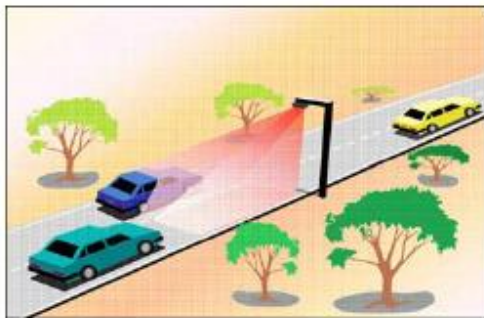
- ▶ depending on the local regulation authority

# The threat :

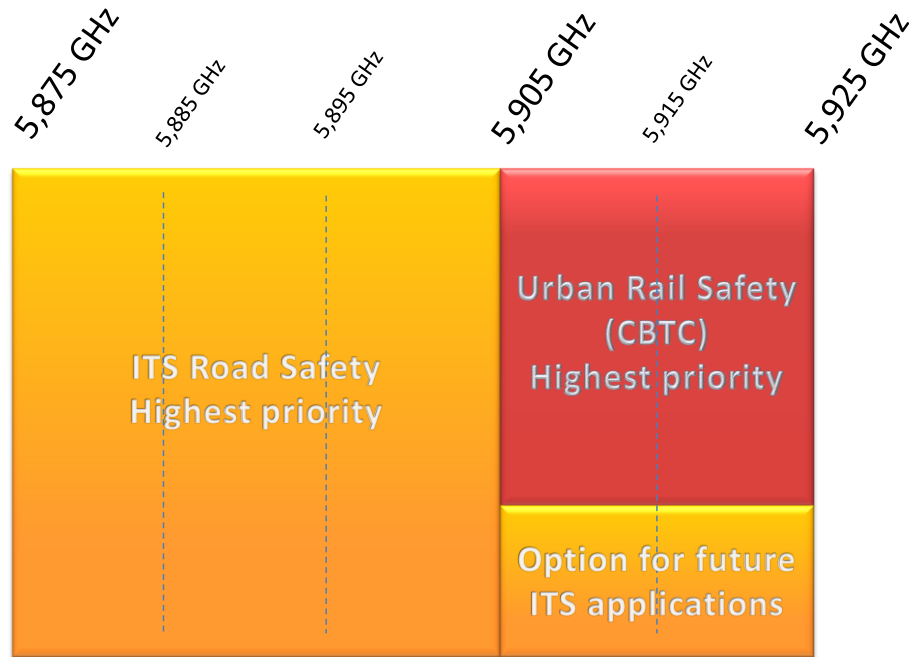
# Intelligent Transport Systems (ITS)

**ITS include telematics and all types of ommunications in vehicles, between vehicles (e.g. car-to-car), and between vehicles and fixed locations (e.g. car-to-infrastructure)**

- ▶ Already owning the 5.875-5.905 GHz band (decision ECC(08)01)
- ▶ With an option toward 5.905-5.925 GHz for future functionalities (confirmed in December 2012)



# Conflicting bandwidth allocation



## Position paper &amp; Spectrum Users Group of UITP

23 November 2015



The automation of existing urban rail lines and the development of fully unattended metro operation (no staff on board) are booming and represent tomorrow's challenges in this sector. Millions of passengers use urban public transport every day (in Europe, 31,6 million daily passengers in 45 cities only for metro), and the European Union's modal shift objective means more people using public transport.



Metro automation is a ...

- proven
- scalable
- adaptable

... solution that meets the needs of diverse mobility scenarios

